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BACKGROUND

How do stress and uncertainty affect decision-making, learning and memory?

Decision-making occurs during navigation and learning. It is widely studied in choice behaviors, but less well understood in natural and more continuous settings, especially under stress and uncertainty. This process could be investigated in rodent spatial navigation, which has been modeled with place-cellbased models. However, traditional models usually ignored **detailed trajectories** or **kinematics**.

Here we extended a place cell-based reinforcement learning model to include detailed kinematics and used it to investigate the role of motivational stress in Morris Water Maze. We performed experiments with two strains of mice learning two versions of the task under different water temperatures: the task with a fixed platform location and the task where platform location varied randomly between two positions. Using computational modeling and parameter estimation, we were able to not only reproduce detailed mouse behaviors but also reveal computational correlates of behavioral differences. Our findings provide insights into computational mechanisms underlying spatial navigation in mice and how various modulators influence it.

trial



and velocities decay with time based on V_{decay} :







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PLACE-CELL-BASED MODEL

The position of the animal (state
$$s(t)$$
) is represented
as a population activity of **'place cells'** (PC):

$$r_j^{pc} = \exp\left(-\frac{\left|\vec{p} - \vec{p}_j\right|^2}{2\sigma_{pc}^2}\right)$$

PCs project to a population of 'action cells' (AC), representing directions of movement $\phi_i \in [0, 2\pi]$.

$$Q^{pc}(s_t, a_t) = r_i^{ac, pc} = \sum_i w_{ii}^{pc} r_i^{pc}$$

Weight update: Weights w_{ii} are initialized as uniformly distributed randoms from $[0, w_{mult}]$ and decay at a rate w_{noise} at each time step, and updated as to decrease the reward prediction error δ :

$$\delta = Reward(t) + \gamma Q_{t+1} - Q_t$$

Iere, γ is temporal reward discounting factor.

 $e_{ii}^{pc} = \lambda e_{ii}^{pc} + r_i^{ac'} r_i^{pc}$, where λ is the eligibility trace decay rate.

Finally, weights are updated as follows: $\Delta w_{ij} = \alpha \, \delta \, e_{ij}$, where α is the learning rate. To simulate realistic trajectories, acceleration constant (*acc*) is applied in the selected direction

 $(v_x, v_y) = ((v_x, v_y) + acc(\cos(\phi_{sel}), \sin(\phi_{sel}))) V_{decay}$ Once the modeled mouse hits the wall, only the tangential component is preserved.



exploration-exploitation dilemma



2 3 4 5 6 7 Day

The comparison was done

parameter

same

under

setting.

 \star DBA/2 mice generally outperform C57BL/6 mice in the standard fixed

platform task.

 \star Mice at 26°C find the platform slower than those at 18°C for both tasks, but the difference disappears or becomes much less significant at the recall session. This indicates stress improves immediate performance, but not so much memory. \star However, both mice trained at 26 °C perform much better when put to 22 °C water after the break (e.g., Time% in target quadrant for C57/BL 6 mice in the fixed platform greatly improved, better than they ever did before). This indicates that although they have been exploring at 26 °C they formed robust knowledge

MODEL COMPARISONS